

Objectives

- Wrapping up implementing BFS and DFS
- Graph Application: Bipartite Graphs

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Review: Comparing BFS vs DFS

- What do they do?
- How are their outcomes different?
- When would we want to use one over the other?

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Review: Comparing BFS vs DFS

- What do they do?
 - Techniques for finding connected components
 - Create a tree of connected components
 - Other uses as well
- How are their outcomes different?
 - BFS: shortest path; bushy tree
 - DFS: spindly tree
- When would we want to use one over the other?
 - BFS: Shortest path
 - DFS: what you'd do in a maze (can't split)

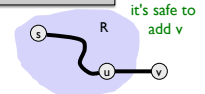
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Review: A General Algorithm for Finding Connected Component

```
R will consist of nodes to which s has a path
R = {s}
while there is an edge (u,v) where u ∈ R and v ∉ R
  add v to R
```



- R will be the **connected component** containing s
- Algorithm is underspecified
 - BFS and DFS say how to consider edges

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Analysis of Connected Components

- For any two nodes s and t in a graph, their connected components are either identical or disjoint
- Proof?

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Analysis of Connected Components

- For any two nodes s and t in a graph, their connected components are either identical or disjoint
- Proof sketch:
 - There is a path between s and $t \rightarrow$ same set of connected components
 - There is no path between s and $t \rightarrow$ disjoint set of connected components

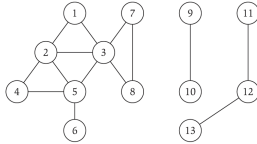
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Set of All Connected Components

- How can we find set of **all** connected components of graph?



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Set of All Connected Components

- How can we find set of all connected components of graph?

```

R* = set of connected components
while there is a node that does not belong to R*
    select s not in R*
    R = {s}
    while there is an edge (u,v) where u ∈ R and v ∉ R
        add v to R
    Add R to R*
  
```

Find s's connected component

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IMPLEMENTATION & ANALYSIS

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Queues and Stacks

- How are queues and stacks similar?
- How are queues and stacks different?

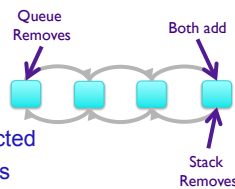
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Queues and Stacks

- Both: doubly linked list
 - Always take first on list
 - Difference in where extracted
 - Have first and last pointers
 - Done in constant time
- Queue: FIFO
 - First in, first out
- Stack: LIFO
 - Last in, first out



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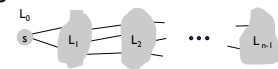
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Review: Breadth-First Search

- Intuition.** Explore outward from s in all possible directions (edges), adding nodes one "layer" at a time

- Algorithm**
 - $L_0 = \{s\}$
 - L_1 = all neighbors of L_0
 - L_2 = all nodes that have an edge to a node in L_1 and do not belong to L_0 or L_1
 - L_{i+1} = all nodes that have an edge to a node in L_i and do not belong to an earlier layer



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Implementing BFS

- What do we need as input?
- What do we need to model?
 - How will we model that?

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Implementing BFS

- Input: Graph as an adjacency list
- Discovered array
- Maintain layers in separate lists, $L[i]$

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Implementing BFS

- Graph: Adjacency list
- Discovered array
- Maintain layers in separate lists, $L[i]$

What does this
stopping condition
mean?

$L[i]$
representation?

```

BFS(s, G):
  Discovered[v] = false, for all v
  Discovered[s] = true
  L[0] = {s}
  layer counter i = 0
  BFS tree T = {}
  while L[i] != {}
    L[i+1] = {}
    for each node u ∈ L[i]
      Consider each edge (u,v) incident to u
      if Discovered[v] == false then
        Discovered[v] = true
        Add edge (u, v) to tree T
        Add v to the list L[i + 1]
    i+=1
  
```

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Analysis

```

BFS(s, G):
  Discovered[v] = false, for all v
  Discovered[s] = true
  L[0] = {s}
  layer counter i = 0
  BFS tree T = {}
  while L[i] != {}
    L[i+1] = {}
    For each node u ∈ L[i]
      Consider each edge (u,v) incident to u
      if Discovered[v] == false then
        Discovered[v] = true
        Add edge (u, v) to tree T
        Add v to the list L[i + 1]
    i+=1
  
```

- $L[i]$ representation? List, queue, or stack
- Doesn't matter because algorithm can consider nodes in any order

What is the running time?

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Analysis

$O(n^2)$

At most n

At most n-1

At most n-1

At most n-1

```

BFS(s, G):
  Discovered[v] = false, for all v
  Discovered[s] = true
  L[0] = {s}
  layer counter i = 0
  BFS tree T = {}
  while L[i] != {}
    L[i+1] = {}
    For each node u ∈ L[i]
      Consider each edge (u,v) incident to u
      if Discovered[v] == false then
        Discovered[v] = true
        Add edge (u, v) to tree T
        Add v to the list L[i + 1]
    i+=1
  
```

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Analysis: Tighter Bound

$O(n^2)$

At most n

At most n-1

At most n-1

At most n-1

```

BFS(s, G):
  Discovered[v] = false, for all v
  Discovered[s] = true
  L[0] = {s}
  layer counter i = 0
  BFS tree T = {}
  while L[i] != {}
    L[i+1] = {}
    For each node u ∈ L[i]
      Consider each edge (u,v) incident to u
      if Discovered[v] == false then
        Discovered[v] = true
        Add edge (u, v) to tree T
        Add v to the list L[i + 1]
    i+=1
  
```

Because we're going to look at each node at most once

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Analysis: Even Tighter Bound

```

BFS(s, G):
  Discovered[v] = false, for all v
  Discovered[s] = true
  L[0] = {s}
  layer counter i = 0
  BFS tree T = {}
  while L[i] != {}
    L[i+1] = {}
    For each node u ∈ L[i]
      Consider each edge (u,v) incident to u
      if Discovered[v] == false then
        Discovered[v] = true
        Add edge (u, v) to tree T
        Add v to the list L[i + 1]
    i+=1

```

At most n

$\sum_{u \in V} \deg(u) = 2m$

$\rightarrow O(n+m)$

$O(\deg(u))$

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Implementing DFS

- What do we need as input?
- What do we need to model?
 - How will we model that?
- Pseudo code

```

DFS(u):
  Mark u as "Explored" and add u to R
  For each edge (u, v) incident to u
    If v is not marked "Explored" then
      DFS(v)

```

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Implementing DFS

- Keep nodes to be processed in a *stack*

```

DFS(s, G):
  Initialize S to be a stack with one element s
  Explored[v] = false, for all v
  Parent[v] = 0, for all v
  DFS tree T = {}
  while S != {}
    Take a node u from S
    if Explored[u] = false
      Explored[u] = true
      Add edge (u, Parent[u]) to T (if u ≠ s)
      for each edge (u, v) incident to u
        Add v to the stack S
        Parent[v] = u

```

How many times is a node added/removed from the stack?

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Analyzing DFS

$O(n+m)$

```

DFS(s, G):
  Initialize S to be a stack with one element s
  Explored[v] = false, for all v
  Parent[v] = 0, for all v
  DFS tree T = {}
  while S != {}
    Take a node u from S
    if Explored[u] = false
      Explored[u] = true
      Add edge (u, Parent[u]) to T (if u ≠ s)
      deg(u) for each edge (u, v) incident to u
        Add v to the stack S
        Parent[v] = u

```

$O(n)$

A node is added/removed from the stack $2m = O(m)$ times

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Looking Ahead

- Reading Chapter 3
 - 3.1-3.3
- Problem Set 3 due before class on Friday

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