

## Objectives

- Review: Closest Pair of Points
- Introduction to Dynamic Programming
  - Review: Fibonacci
  - Weighted interval scheduling

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1

## Review

- What is the D&C algorithm for finding the closest pair of points?
- What is the key insight that leads to an  $O(n \log n)$  algorithm?

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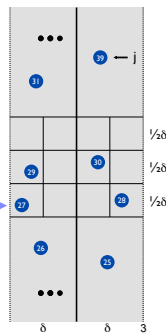
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2

## Analyzing Cost of Combining

Prepare minds to be blown...

- **Def.** Let  $s_i$  be the point in the  $2\delta$ -strip, with the  $i^{\text{th}}$  smallest y-coordinate
- **Claim.** If  $|i - j| \geq 12$ , then the distance between  $s_i$  and  $s_j$  is at least  $\delta$ 
  - What is the distance of the box?  $i \rightarrow$
  - How many points can be in a box?
  - When do we know that points are  $> \delta$  apart?



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3

## Review

- What was the new problem-solving technique we started to discuss on Monday?

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## Dynamic Programming Memoization Process

- Create a table with the possible inputs
- If the value is in the table, return it, without recomputing it
- Otherwise, call function recursively
  - Add value to table for future reference

How can we apply this template to our Fibonacci problem?

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5

## Memoization Example: Fibonacci

```
memoized_fibonacci(n):
    for j = 1 to n:
        results[j] = -1      # -1 means undefined
    return memoized_fib_recurs(results, n)

memoized_fib_recurs(results, n):
    if results[n] != -1:     # value is defined
        return results[n]
    if n == 1:
        val = 1
    elif n == 2:
        val = 1
    else:
        val = memoized_fib_recurs(results, n-2)
        val = val + memoized_fib_recurs(results, n-1)
        results[n] = val
    return val
```

Runtime?

 $O(n)$ 

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6

## Memoization Example: Fibonacci

Alternative version...

```
memoized_fibonacci(n):
    for j = 1 to n:
        results[j] = -1 # -1 means undefined
    results[1] = 1
    results[2] = 1

    return memoized_fib_recurs(results, n)

memoized_fib_recurs(results, n):
    if results[n] != -1: # value is defined
        return results[n]

    val = memoized_fib_recurs(results, n-2)
    val = val + memoized_fib_recurs(results, n-1)
    results[n] = val
    return val
```

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7

## WEIGHTED INTERVAL SCHEDULING

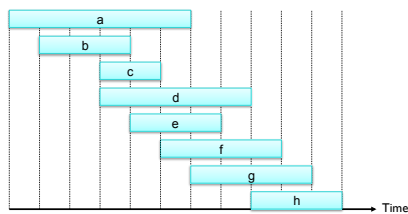
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## Weighted Interval Scheduling

- Job  $j$  starts at  $s_j$ , finishes at  $f_j$ , and has weight or value  $v_j$
- Two jobs are **compatible** if they don't overlap
- Goal:** find **maximum weight** subset of mutually compatible jobs



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## Unweighted Interval Scheduling Review

- Recall.** Greedy algorithm works if all weights are 1 (or equivalent).
  - Consider jobs in ascending order of finish time
  - Add job to subset if it is compatible with previously chosen jobs

What happens to Greedy algorithm if we add weights to the problem?

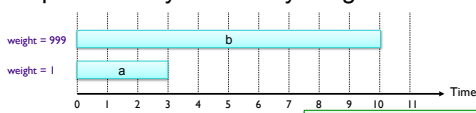
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## Limitation of Greedy Algorithm

- Recall.** Greedy algorithm works if all weights are 1.
  - Consider jobs in ascending order of finish time
  - Add job to subset if it is compatible with previously chosen jobs
- Observation.** Greedy algorithm can fail spectacularly if arbitrary weights are allowed



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Any other greedy approaches?

## Limitations of Greedy Algorithms

- Need to consider weight
  - No greedy algorithm works
- Need a more complex algorithm to solve problem

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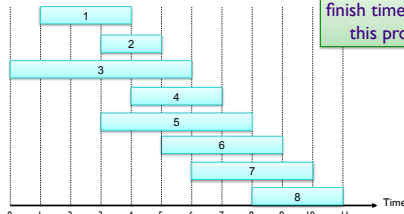
12

## Weighted Interval Scheduling

**Notation.** Label jobs by finishing time:  $f_1 \leq f_2 \leq \dots \leq f_n$

**Def.**  $p(j)$  = largest index  $i < j$  such that job  $i$  is compatible with  $j$

**Ex:**  $p(8) = 5$ ,  $p(7) = 3$ ,  $p(2) = 0$



Why is ordering by finish time useful in this problem?

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13

## Dynamic Programming

- Assume we have an optimal solution
- OPT(j)** = value of optimal solution to the problem consisting of job requests 1, 2, ..., j

What is something obvious we can say about the optimal solution with respect to job j?

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14

## Dynamic Programming: Binary Choice

- OPT(j)** = value of optimal solution to the problem consisting of job requests 1, 2, ..., j

➤ Case 1: OPT selects job j

➤ Case 2: OPT does not select job j

Explore both of these cases...

- What jobs are in OPT? Which are not?

Keep in mind our definition of p

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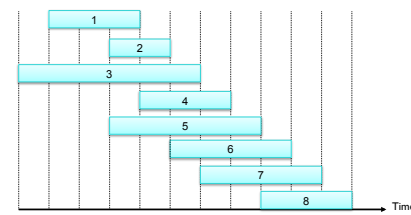
15

## Weighted Interval Scheduling

**Notation.** Label jobs by finishing time:  $f_1 \leq f_2 \leq \dots \leq f_n$

**Def.**  $p(j)$  = largest index  $i < j$  such that job  $i$  is compatible with j

**Ex:**  $p(8) = 5$ ,  $p(7) = 3$ ,  $p(2) = 0$



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16

## Dynamic Programming: Binary Choice

- OPT(j)** = value of optimal solution to the problem consisting of job requests 1, 2, ..., j

➤ Case 1: OPT selects job j

- can't use incompatible jobs  $\{ p(j) + 1, p(j) + 2, \dots, j - 1 \}$
- must include optimal solution to problem consisting of remaining compatible jobs 1, 2, ...,  $p(j)$

➤ Case 2: OPT does **not** select job j

- must include optimal solution to problem consisting of remaining compatible jobs 1, 2, ...,  $j-1$

Formulate **OPT(j)** as a recurrence relation

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17

## Dynamic Programming: Binary Choice

- OPT(j)** = value of optimal solution to the problem consisting of job requests 1, 2, ..., j

➤ Case 1: OPT selects job j

- can't use incompatible jobs  $\{ p(j) + 1, p(j) + 2, \dots, j - 1 \}$
- must include optimal solution to problem consisting of remaining compatible jobs 1, 2, ...,  $p(j)$

➤ Case 2: OPT does **not** select job j

- must include optimal solution to problem consisting of remaining compatible jobs 1, 2, ...,  $j-1$

Formulate **OPT(j)** in terms of smaller subproblems  
Which should we choose?

Two options:  $\text{Opt}(j) = v_j + \text{Opt}(p(j))$   
 $\text{Opt}(j) = \text{Opt}(j-1)$

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18

## Dynamic Programming: Binary Choice

- $\text{OPT}(j)$  = **value** of optimal solution to the problem consisting of job requests  $1, 2, \dots, j$ 
  - **Case 1: OPT selects job  $j$** 
    - can't use incompatible jobs  $\{p(j) + 1, p(j) + 2, \dots, j - 1\}$
    - must include optimal solution to problem consisting of remaining compatible jobs  $1, 2, \dots, p(j)$
  - **Case 2: OPT does **not** select job  $j$** 
    - must include optimal solution to problem consisting of remaining compatible jobs  $1, 2, \dots, j - 1$

$$\text{Opt}(j) = \begin{cases} 0 & j=0 \\ \max\{v_j + \text{Opt}(p(j)), \text{Opt}(j-1)\} & \text{Otherwise} \end{cases}$$

Basecase  
Choose the "better" of the two solutions

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19

## Weighted Interval Scheduling: Recursive Algorithm

Input:  $n$  jobs (associated start time  $s_j$ , finish time  $f_j$ , and value  $v_j$ )

Sort jobs by finish times so that  $f_1 \leq f_2 \leq \dots \leq f_n$

Compute  $p(1), p(2), \dots, p(n)$     **Closest compatible job**

Compute-Opt( $j$ ):

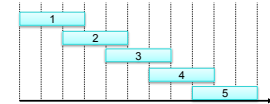
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if  $j = 0$ 
    return 0
else
    return  $\max(v_j + \text{Compute-Opt}(p(j)), \text{Compute-Opt}(j-1))$ 

```

Picks  $j$       Doesn't pick  $j$

What is the runtime?  
(Trace for  $n = 5$ )



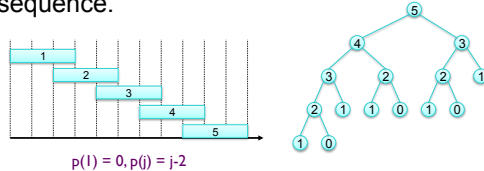
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20

## Weighted Interval Scheduling: Brute Force

- **Observation.** Redundant sub-problems  $\Rightarrow$  exponential algorithms
- Ex. Number of recursive calls for family of "layered" instances grows like Fibonacci sequence.



$p(1) = 0, p(j) = j-2$

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21

## Weighted Interval Scheduling: Memoization

- Store results of each sub-problem in a cache; lookup as needed.

Input:  $n$  jobs (associated start time  $s_j$ , finish time  $f_j$ , and value  $v_j$ )

Sort jobs by finish times so that  $f_1 \leq f_2 \leq \dots \leq f_n$

Compute  $p(1), p(2), \dots, p(n)$

for  $j = 1$  to  $n$

$M[j] = \text{empty}$

$M[0] = 0$

**M-Compute-Opt( $n$ )**

```

M-Compute-Opt( $j$ ):
if  $M[j]$  is empty:
     $M[j] = \max(v_j + \text{M-Compute-Opt}(p(j)), \text{M-Compute-Opt}(j-1))$ 
return  $M[j]$ 

```

global array      Call function with initial input

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## Looking Ahead

- PS7 due Friday
- SSA EC soon
- Exam 2 handed out Friday

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23