

Objectives

- Dynamic Programming
 - Segmented Least Squares
 - Subset Sums problem

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Review: Weighted Interval Scheduling

- Jobs have start time, end time, value/weight
 - Goal: schedule compatible jobs with maximum weight
- What was the key insight to solving the weighted interval scheduling problem?

Binary decision:

- Optimal solution for jobs i through j includes j or doesn't

- How do we pick the solution?

Choose the larger value of

- [choose j and the best solution of compatible jobs] OR [best solution if don't pick j]

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Then what did we do?

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Review

- What is the process for applying dynamic programming to a problem?

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Dynamic Programming Process

- Determine optimal substructure of problem
 - Define the recurrence relation
- Define algorithm to find the **value** of optimal solution
- Optionally, change algorithm to an **iterative** rather than recursive solution
- Define algorithm to find **optimal solution**
- Analyze running time of algorithms

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SEGMENTED LEAST SQUARES

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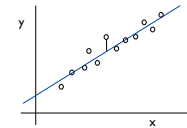
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Least Squares

- Foundational problem in statistic and numerical analysis
- Given n points in the plane: $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$
- Find a line $y = ax + b$ that minimizes the sum of the squared error
 - "line of best fit"

Sum of squared error:

$$SSE = \sum_{i=1}^n (y_i - ax_i - b)^2$$



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Least Squares

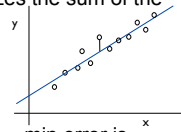
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- Find a line $y = ax + b$ that minimizes the sum of the squared error
 - "line of best fit"

Sum of squared error

$$SSE = \sum_{i=1}^n (y_i - ax_i - b)^2$$

- Closed form solution. Calculus \Rightarrow min error is achieved when

$$a = \frac{n \sum x_i y_i - (\sum x_i)(\sum y_i)}{n \sum x_i^2 - (\sum x_i)^2}, \quad b = \frac{\sum y_i - a \sum x_i}{n}$$



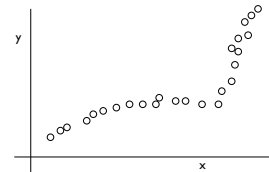
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Least Squares

- What happens to the error if we try to fit one line to these points?



- What pattern does it seem like these points have?

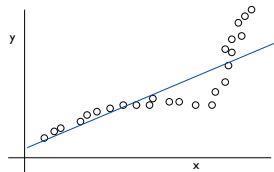
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Least Squares

- What happens to the error if we try to fit one line to these points?
 - Large error



- Pattern: More like 3 lines

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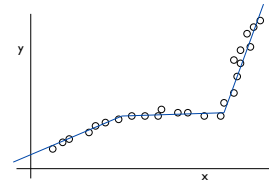
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Segmented Least Squares

- Points lie roughly on a **sequence** of line segments
- Given n points in the plane $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ with $x_1 < x_2 < \dots < x_n$, find a **sequence of line segments** that **minimizes $f(x)$**

If I want the **best** fit, how many lines should I use?



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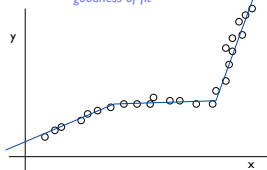
Segmented Least Squares

- Points lie roughly on a **sequence** of line segments
- Given n points in the plane $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ with $x_1 < x_2 < \dots < x_n$, find a sequence of line segments that **minimizes $f(x)$**

What's a reasonable choice for $f(x)$ to balance accuracy and parsimony?

goodness of fit

number of lines



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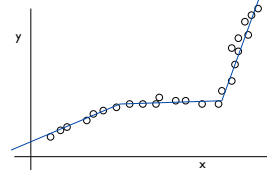
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Segmented Least Squares

- Points lie roughly on a **sequence** of several line segments.
- Given n points in the plane $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ with $x_1 < x_2 < \dots < x_n$, find a sequence of line segments that minimizes:
 - E : sum of the sums of the squared errors in each segment
 - L : the number of lines
- Tradeoff function: $E + cL$, for some constant $c > 0$.

How should we define an optimal solution?



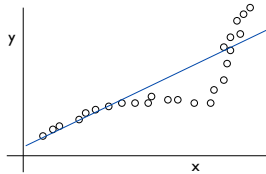
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Segmented Least Squares

- What made it seem like the points were in 3 lines? What happened?



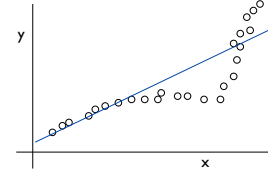
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Segmented Least Squares

- What made it seem like the points were in 3 lines? What happened?



- Error increased
- Looking for *change* in linear approximation
 - Where to partition points into line segments

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Recall:

Properties of Problems for DP

- Polynomial number of subproblems
- Solution to original problem can be easily computed from solutions to subproblems
- Natural ordering of subproblems, easy to compute recurrence

We need to:

- Figure out how to break the problem into subproblems
- Figure out how to compute solution from subproblems
- Define the recurrence relation between the problems

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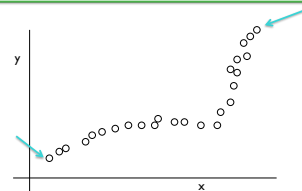
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Toward a Solution

- Consider just the first or last point

What do we know about those points?
their segments? cost of a segment?



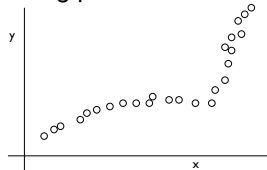
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Toward a Solution

- p_n can only belong to one segment
 - Segment: p_i, \dots, p_n
 - Cost: c (cost for segment) + error of segment
- What is the remaining problem?



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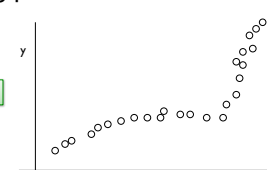
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Toward a Solution

- p_n can only belong to one segment
 - Segment: p_i, \dots, p_n
 - Cost: c (cost for segment) + error of segment
- What is the remaining problem?
 - Solve for p_1, \dots, p_{i-1}

Next: Formulate as a recurrence



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Dynamic Programming: Multiway Choice

- **Notation.**
 - **OPT(j)** = minimum cost for points p_1, p_{i+1}, \dots, p_j .
 - **e(i, j)** = minimum sum of squares for points p_i, p_{i+1}, \dots, p_j .
- How do we compute OPT(j)?
 - Last problem: binary decision (include job or not)
 - This time: **multiway** decision
 - Which option do we choose?

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Dynamic Programming: Multiway Choice

- **Notation.**
 - **OPT(j)** = minimum cost for points p_1, p_{i+1}, \dots, p_j .
 - **e(i, j)** = minimum sum of squares for points p_i, p_{i+1}, \dots, p_j .
- To compute OPT(j):
 - Last segment contains points p_i, p_{i+1}, \dots, p_j for some i
 - Cost = $e(i, j) + c + \text{OPT}(i-1)$.

$$\text{OPT}(j) = \begin{cases} 0 & \text{if } j=0 \\ \min_{1 \leq i \leq j} \{ e(i, j) + c + \text{OPT}(i-1) \} & \text{otherwise} \end{cases}$$

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Segmented Least Squares: Algorithm

```

INPUT: n, p1, ..., pN, c
Segmented-Least-Squares()
  M[0] = 0
  e[0][0] = 0 # needed?
  for j = 1 to n
    for i = 1 to j
      e[i][j] = least square error for the
                segment pi, ..., pj

    for j = 1 to n
      M[j] = min1 ≤ i ≤ j (e[i][j] + c + M[i-1])
  return M[n]

```

Costs?

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Segmented Least Squares: Algorithm Analysis

How do we find the solution?

```

INPUT: n, p1, ..., pN, c
Segmented-Least-Squares()
  M[0] = 0
  e[0][0] = 0
  for j = 1 to n
    for i = 1 to j
      e[i][j] = least square error for the
                segment pi, ..., pj
      O(n3)

    for j = 1 to n
      M[j] = min1 ≤ i ≤ j (e[i][j] + c + M[i-1])
      O(n2)
  return M[n]

```

can be improved to O(n²) by pre-computing various statistics

- Bottleneck: computing e(i, j) for O(n²) pairs, O(n) per pair using previous formula

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Post-Processing: Finding the Solution

```

FindSegments(j):
  if j = 0:
    output nothing
  else:
    Find an i that minimizes ei,j + c + M[i-1]
    Output the segment {pi, ..., pj}
    FindSegments(i-1)

```

Cost? O(n²)

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Dynamic Programming Process

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SUBSET SUMS and KNAPSACKS

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The Price is Right

Or, shopping with someone else's money

- **Goal:** Spend as much money as possible without going over \$100

- CD \$18
- Jeans \$40
- DVD \$35
- Dinner \$15
- Book \$8
- Ice cream \$5
- Shoes \$62
- Pizza \$7

Possible solutions?

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Knapsack Problem

- Given n objects and a "knapsack"
- Item i weighs $w_i > 0$ kilograms and has value $v_i > 0$
 - Alternative: jobs require w_i time
- Knapsack has capacity of W kilograms
 - Alternative: W is time interval that resource is available

Goal: fill knapsack so as to maximize total **value**

$W = 11$

Item	Value	Weight
1	1	1
2	6	2
3	18	5
4	22	6
5	28	7

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Towards a Recurrence...

- What do we know about the knapsack with respect to item i ?

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Towards a Recurrence...

- What do we know about the knapsack with respect to item i ?
 - Either select item i or not
 - If don't select
 - Pick optimum solution of remaining items
 - Otherwise
 - What happens?
 - How does problem change?

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Dynamic Programming: False Start

- **Def.** $OPT(i)$ = max profit subset of items 1, ..., i
 - **Case 1:** OPT does not select item i
 - OPT selects best of $\{1, 2, \dots, i-1\}$
 - **Case 2:** OPT selects item i
 - Accepting item i does not immediately imply that we will have to reject other items
 - No known conflicts
 - Without knowing what other items were selected before i , we don't even know if we have enough room for i

➡ Need more sub-problems!

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Looking Ahead

- Exam 2 due next Friday
 - Wednesday work period
- No wiki for next week