

Objectives

- Minimum Spanning Tree
- Union-Find Data Structure
- Clustering

Review

- What does the acronym MST stand for?
 - What is an MST?
- What are some algorithms to find the MST?
- What did we prove about the intersection of cycles and cut sets?
- How do we prove the following:
 - **Cut property.** Let S be any subset of nodes, and let e be the min cost edge with exactly one endpoint in S . Then the MST T^* contains e .
 - **Pf.** (exchange argument)
 - Suppose there is an MST T^* that does not contain e
 - What do we know about T , by defn?
 - What do we know about the nodes e connects?

Proving Cut Property: OK to Include Edge

- Simplifying assumption: All edge costs c_e are distinct.
- **Cut property.** Let S be any subset of nodes, and let e be the **min cost edge** with exactly one endpoint in S .
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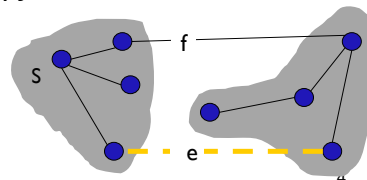
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Proving Cut Property: OK to Include Edge

- **Cut property.** Let S be any subset of nodes, and let e be the **min cost edge** with exactly one endpoint in S .
Then the MST T^* contains e .
- Pf. (exchange argument)
 - Suppose there is an MST T^* that does not contain e
 - Adding e to T^* creates a cycle C in T^*
 - Edge e is in cycle C and in cutset corresponding to S
 - ⇒ there exists another edge, say f , that is in both C and S 's cutset

Which means?



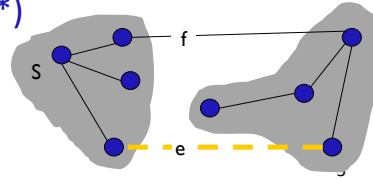
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Proving Cut Property: OK to Include Edge

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 - Suppose there is an MST T^* that does not contain e
 - Adding e to T^* creates a cycle C in T^*
 - Edge e is in cycle C and in cutset corresponding to S
 - ⇒ there exists another edge, say f , that is in both C and S 's cutset
 - $T' = T^* \cup \{e\} - \{f\}$ is also a spanning tree
 - Since $c_e < c_f$, $\text{cost}(T') < \text{cost}(T^*)$
 - This is a contradiction. ■



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Proving Cycle Property: OK to Remove Edge

- **Simplifying assumption:** All edge costs c_e are distinct
- **Cycle property.** Let C be any cycle in G , and let f be the **max cost edge** belonging to C . Then the MST T^* does not contain f .

Ideas about approach?

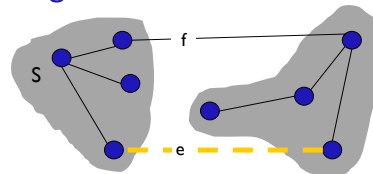
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Cycle Property: OK to Remove Edge

- **Cycle property.** Let C be any cycle in G , and let f be the **max cost edge** belonging to C . Then the MST T^* does not contain f .
- **Pf.** (exchange argument)
 - Suppose f belongs to T^*
 - Deleting f from T^* creates a cut S in T^*
 - Edge f is both in the cycle C and in the cutset S
 - ⇒ there exists another edge, say e , that is in both C and S
 - $T' = T^* \cup \{e\} - \{f\}$ is also a spanning tree
 - Since $c_e < c_f$, $\text{cost}(T') < \text{cost}(T^*)$
 - This is a contradiction. ■



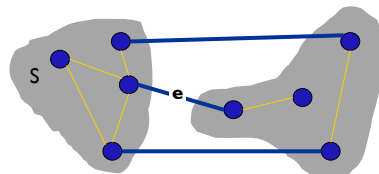
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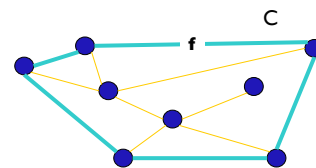
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Summary of What We Proved

- **Simplifying assumption:** All edge costs c_e are distinct
 - MST is unique
- **Cut property.** Let S be any subset of nodes, and let e be the **min cost edge** with exactly one endpoint in S . Then MST contains e .
- **Cycle property.** Let C be any cycle, and let f be the **max cost edge** belonging to C . Then MST does not contain f .

Cut Property: e is in MST

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Cycle Property: f is **not** in MST

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Prim's Algorithm

[Jarník 1930, Dijkstra 1957, Prim 1959]

- Start with some root node s and greedily grow a tree T from s outward.
- At each step, add the cheapest edge e to T that has exactly one endpoint in T .

How can we prove its correctness?

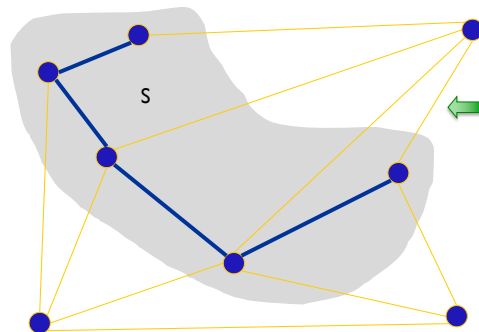
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Prim's Algorithm: Proof of Correctness

- Initialize S to be any node
- Apply **cut property** to S
 - Add min cost edge (v, u) in *cutset* corresponding to S , and add one new explored node u to S



Ideas about implementation?

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Implementation: Prim's Algorithm

Similar to Dijkstra's algorithm

- Maintain set of explored nodes S
- For each unexplored node v , maintain attachment cost $a[v] \rightarrow$ cost of cheapest edge v to a node in S

Running Time?

```

foreach ( $v \in V$ )  $a[v] = \infty$ 
Initialize an empty priority queue  $Q$ 
foreach ( $v \in V$ ) insert  $v$  onto  $Q$ 
Initialize set of explored nodes  $S = \phi$ 
while ( $Q$  is not empty)
   $u =$  delete min element from  $Q$ 
   $S = S \cup \{u\}$ 
  foreach (edge  $e = (u, v)$  incident to  $u$ )
    if ( $(v \notin S)$  and ( $c_e < a[v]$ ))
      decrease priority  $a[v]$  to  $c_e$ 
  
```

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Implementation: Prim's Algorithm

Similar to Dijkstra's algorithm

- Maintain set of explored nodes S
- For each unexplored node v , maintain attachment cost $a[v] \rightarrow$ cost of cheapest edge v to a node in S

$O(m \log n)$ with a heap

```

foreach ( $v \in V$ )  $a[v] = \infty$   $O(n)$ 
Initialize an empty priority queue  $Q$ 
foreach ( $v \in V$ ) insert  $v$  onto  $Q$   $O(n \log n)$ 
Initialize set of explored nodes  $S = \phi$ 
while ( $Q$  is not empty)  $O(n)$ 
   $u =$  delete min element from  $Q$   $O(\log n)$ 
   $S = S \cup \{u\}$ 
  foreach (edge  $e = (u, v)$  incident to  $u$ )  $O(\deg(u))$ 
    if ( $(v \notin S)$  and ( $c_e < a[v]$ ))
      decrease priority  $a[v]$  to  $c_e$   $O(\log n)$ 
  
```

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Kruskal's Algorithm [1956]

- Start with $T = \phi$
- Consider edges in *ascending order of cost*
- Insert edge e in T unless doing so would create a cycle
 - Add edge as long as “compatible”

How can we prove algorithm's correctness?

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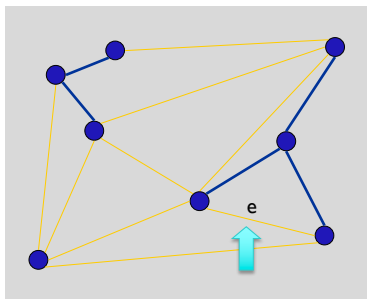
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Kruskal's Algorithm: Proof of Correctness

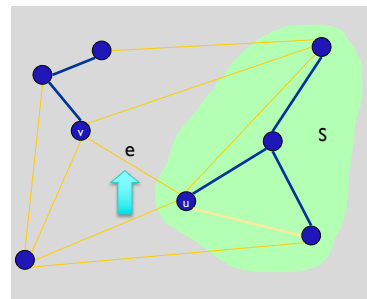
What is tricky about implementing Kruskal's algorithm?

- Consider edges in ascending order of weight
- **Case 1:** If adding e to T creates a cycle, discard e according to **cycle property** (e must be max weight)
- **Case 2:** Otherwise, insert $e = (u, v)$ into T according to **cut property** where $S =$ set of nodes in u 's *connected component*



Case 1

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Case 2

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Implementing Kruskal's Algorithm

What is tricky about implementing Kruskal's algorithm?

How do we know when adding an edge will create a cycle?

- What are the properties of a graph/its nodes when adding an edge will create a cycle?

UNION-FIND DATA STRUCTURE

Union-Find Data Structure

- Keeps track of a graph as edges are added
 - Cannot handle when edges are deleted
- Maintains disjoint sets
 - E.g., graph's connected components
- Operations/API:
 - **Find(u)**: returns name of set containing u
 - How utilized to see if two nodes are in the same set?
 - Goal implementation: **$O(\log n)$**
 - **Union(A, B)**: merge sets A and B into one set
 - Goal implementation: **$O(\log n)$**

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Best darn Union-Find Data Structure

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Implementing Kruskal's Algorithm

- Using the **union-find** data structure
 - Build set T of edges in the MST
 - Maintain set for each connected component

Costs?

```

Sort edge weights so that  $c_1 \leq c_2 \leq \dots \leq c_m$ 
T = {}
foreach (u ∈ V) make a set containing singleton u

for i = 1 to m
    (u,v) = ei
    if (u and v are in different sets)
        T = T ∪ {ei}
        merge the sets containing u and v
return T
  
```

are u and v in different connected components?

merge two components

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Looking Ahead

- Wiki: 4.5-4.7
- PS7 – next Friday